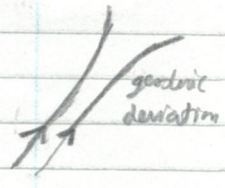
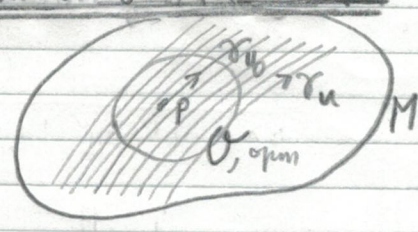
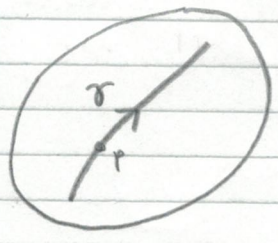


§5 SECOND VARIATION OF ARCLength

§5.1 Introduction



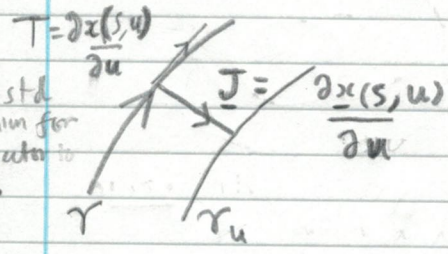
1 geodesic involves Γ
 hille manifold,
 much of
 ec-answe
 grouped with
 it as well.

looking around a pt p locally involves multiple geodesics.
 \leftrightarrow curvature R
 \sim a non-intersecting family: a congruence
 1-parameter u in the 2d picture.
 per family u .

A congruence in $O \subset M$ is a family of curves
 st. precisely one curve in this family passes through each point $q \in O$.

There is a 1:1 correspondence between a congruence and the v.f. of its tangents in O .
 We consider this in §5.2.

Another characterization is in terms of a family of varied curves

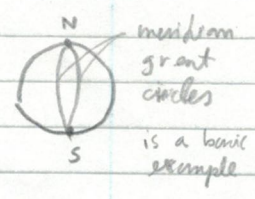
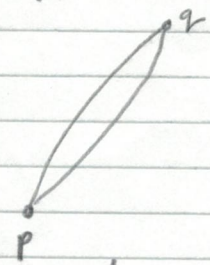


s the arclength along the geodesic.
 γ_u is still restricted to itself be a geodesic.
 (so it's a restricted family of varied curves).

We consider this in §5.3. It is a fast route to obtaining a d.e. for geodesic deviation.

\leftrightarrow We then approach this in a more general manner from a variational principle in §5.4-5.5
 (2nd variation of arc, to geodesics arising from 1st variation)

One of the most interesting features is that of virtual re-intersection of two geodesics originating from a given point:



into
 results
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 minimal
 es.
 ≤ 0
 all minima
 ric calculus

§5.6) The points p and q are then called conjugate. \leftrightarrow Jacobi field vanishes at p, q .

The existence or otherwise of conjugate points turns out to quite often be useful in proofs by contradiction.

In particular, conjugate points are considered in the manner in proof of the GR Singularity Thm. (the Jacobi test for maximum)

We finally simplify the 2nd variation using an index presentation in §5.7, allowing us to tap in to some basic ODE theory. Curvature sign dependent results ensue from §5.5-7.